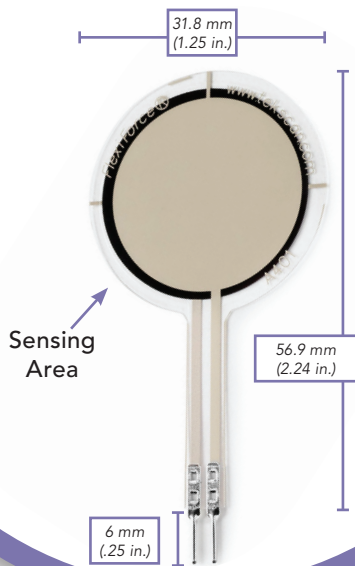


## Actual size of sensor



# FlexiForce™

## Standard Model A401

The FlexiForce A401 is our standard piezoresistive force sensor with the largest sensing area. It is available off-the-shelf for easy proof of concept and is also available in large volumes for design-in applications. The A401 can be used with our test & measurement, prototyping, and embedding electronics, including the OEM Development Kit, FlexiForce Quickstart Board, and the ELF™ System\*. You can also use your own electronics, or multimeter.



## Physical Properties

Thickness	0.203 mm (0.008 in.)
Length	56.9 mm (2.24 in.)**
Width	31.8 mm (1.25 in.)
Sensing Area	25.4 mm (1 in.) diameter
Connector	2-pin Male Square Pin
Substrate	Polyester
Pin Spacing	2.54 mm (0.1 in.)

## Benefits

- Thin and flexible
- Easy to use
- Convenient and affordable

✓ ROHS COMPLIANT

\* Sensor will require an adapter/extender to connect to the ELF System. Contact your Tekscan representative for assistance.

\*\*Length does not include pins. Please add approximately 6 mm (0.25 in.) for pin length for a total length of approximately 32 mm (1.25 in.).

## Standard Force Ranges as Tested with Circuit Shown

111 N (0 - 25 lb)<sup>†</sup>

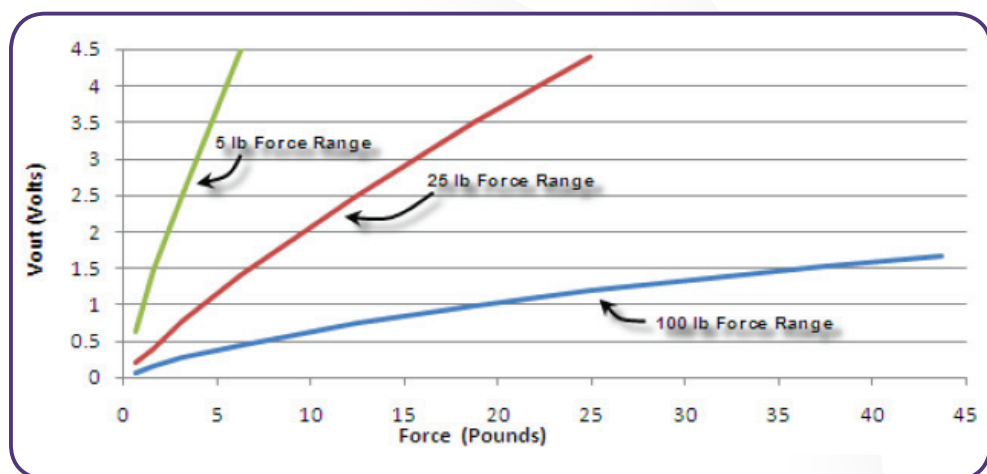
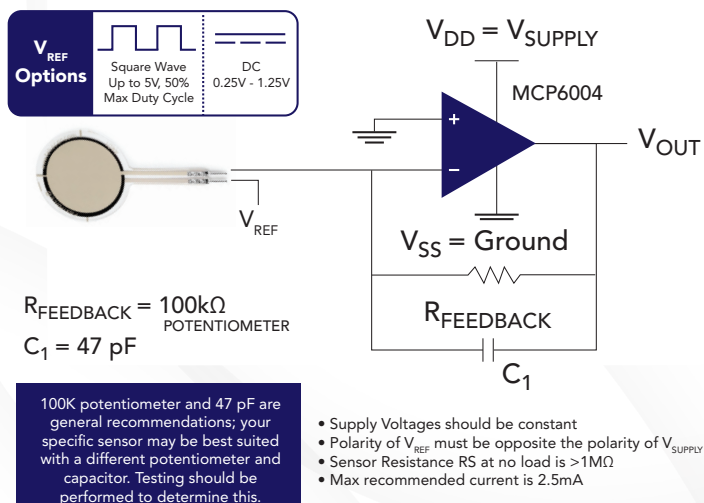
<sup>†</sup>This sensor can measure up to 31,138 N (7,000 lb).

The force range can be extended by reducing the drive voltage,  $V_T$ , or the resistance value of the feedback resistor,  $R_F$ . Conversely, the sensitivity can be increased for measurement of lower forces by increasing  $V_T$  or  $R_F$ .

Sensor output is a function of many variables, including interface materials. Therefore, Tekscan recommends the user calibrate each sensor for the application. The graph below-right is an illustration of how a sensor can be used to measure varying force ranges by changing the feedback resistor (the graph below-right should not be used as a calibration chart).

## Recommended Circuit

$$V_{OUT} = -V_T * (R_F / R_S)$$



	Typical Performance	Evaluation Conditions
Linearity (Error)	< $\pm 3\%$ of full scale	Line drawn from 0 to 50% load
Repeatability	< $\pm 2.5\%$	Conditioned sensor, 80% of full force applied
Hysteresis	< 4.5% of full scale	Conditioned sensor, 80% of full force applied
Drift	< 5% per logarithmic time scale	Constant load of 111 N (25 lb)
Response Time	< 5 $\mu$ sec	Impact load, output recorded on oscilloscope
Operating Temperature	-40°C - 60°C (-40°F - 140°F)	Convection and conduction heat sources
Acceptance Criteria	$\pm 40\%$ sensor-to-sensor variation	

**\*All data above was collected utilizing an Op Amp Circuit.** If your application cannot allow an Op Amp Circuit, visit [www.tekscan.com/flexiforce-integration-guides](http://www.tekscan.com/flexiforce-integration-guides), or contact a FlexiForce Applications Engineer.

Force reading change per degree of temperature change = 0.36%/°C ( $\pm 0.2\%$ /°F).



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