Torque Sensor Read Out Unit



Quick Start Guide



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1. Short description

This document is a short guide for connecting and using the read out unit together with standard NCTE torque sensor families.

2. Basic connection diagram



ver	R	ead Out Unit	DC Power Supply		
	Pin	Label	Description		
Ρον	3	V+	Supply Voltage + (+15 30 VDC)		
	2	GND	Supply Voltage – (GND)		





On Windows the read out unit is installed as HID and does not require special drivers.
The MG-ME1 PC Software runs as is and needs no further installation. It can be downloaded at www.ncte.com.







Sensor	Read Out Unit		Sensor Series 2000 (Connector: Binder Series 712)		Sensor Series 3000 / 4000 (Connector: Binder Series 423/723/425)		Sensor Series 7000 (Connector: Binder Series M16 Connector IP67)				
	Pin	Label	Pin	Color	Description	Pin	Color	Description	Pin	Color	Description
	14	a. GND	-	-	-	D	Yellow	Analog GND	Е	Grey	Analog GND
	15	ENCB	-	-	-	н	Red	Angle Ch B	D	Yellow	Angle Channel B
	16	ENCA	-	-	-	F	Pink	Angle Ch A	с	Green	Angle Channel A
	17	AIN	2	Brown	Signal Output V _{out}	С	Green	Analog Out	F	Pink	Analog voltage signal output
	20	GND	3	Black	Ground	В	Brown	Ground GND	G	Blue	Ground GND
	21	+12V	1	White	Supply voltage V _{CC}	S	White	Supply voltage V _{CC}	Н	Red	Supply voltage V _{CC}

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Torque Input:

MGME1	-PC ver. 1,05								
Connecte	Connected to MG-ME1 ver.: 1,07								
	Measurement Chart Data acquisition 🔀 Device settings								
\cup									
\frown	0.10 V input config (torque) Enc. input config (position/speed)								
(2)	V):	Actual measure.: Off	fset: Counts per re	volution Actual measure.:					
	ent: Torque unit:	Decmal point: Co	efficient: Speed unit:	Set zero					
Offset 0,00	[N]	Save 0	cimal point: Position unit: ▼ counts ▼	Save 3					
Measuren Trigger sc Continue	nent trigger Nurce: Period Dus • 1s •	Output PK1 config Source: Torque	Output PK2 config Glob Source: Defi Torque Tor	al settings ault display after power on rque					
Trig. start 20,0000	t level Trig. stop level 2,0000	PK On threshold 500,00	PK On threshold: Mod 1000,00 1	bus address					
Save :	to SD card	PK Off threshold: 2000,00	PK Off threshold: Mod 2500,00 57	lbus baudrate 600 👻					
	Save Save	Save Save	Save	Save Save					
	A R	ead settings	Factory settings	,					
Status: 0-1	0V input config saved			Data acquisition: 🥥					

- 1. Select decimal precision for torque display and data recording and press the **[Save]** button.
- While sensor is unloaded (zero torque) press the [Set zero] button. This determines the zero point of the analog Signal (usually ≈ 2.5 V or ≈ 5 V)
 Insut Operfisient end press the [Court button The
- 3. Input Coefficient and press the **[Save]** button. The coefficient can be calculated using the slope value of the calibration certificate as follows:



Example:

$$Coefficient = \frac{1}{40.02 \frac{mV}{Nm}} \times 1000 = 24.9875 \frac{Nm}{V}$$

Encoder Input:

MGME1-PC ver. 1,05

- Input the encoders no. of pulses per revolution and press the [Save] button.
 Activate the "Auto reset" Check Box and press the
- [Save] button. When active the position value is reset to 0 after a full revolution.
- Input the coefficient for speed and position calculation and press the [Save] button. The coefficient can be calculated as follows:

$$Coefficient = \frac{1}{Counts _ per _ revolution}$$

Example:

$$Coefficient = \frac{1}{360} \approx 2.77777777777 = -3$$

- 4. Select the time unit for the speed display and press the **[Save]** button.
- 5. Set the position unit to "Revol" (=revolution) and press the **[Save]** button.



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4. Measurement data displays

The PC Software has two tabs which can display live measurement data

- "Measurement" tab: numerical displays
- "Chart" tab: data plot with various editable properties, print option and image export.





5. Setting up data acquisition (PC)



- 1. Press [Save file path] and select both path and name for the csv-file.
- 2. Check the check box in order to start the aquisition. *If* the file already exists, new data will be appended at the end of the file.

<section-header> 6. Contact A Contact A Subserve that a sequence of the sequence of

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